

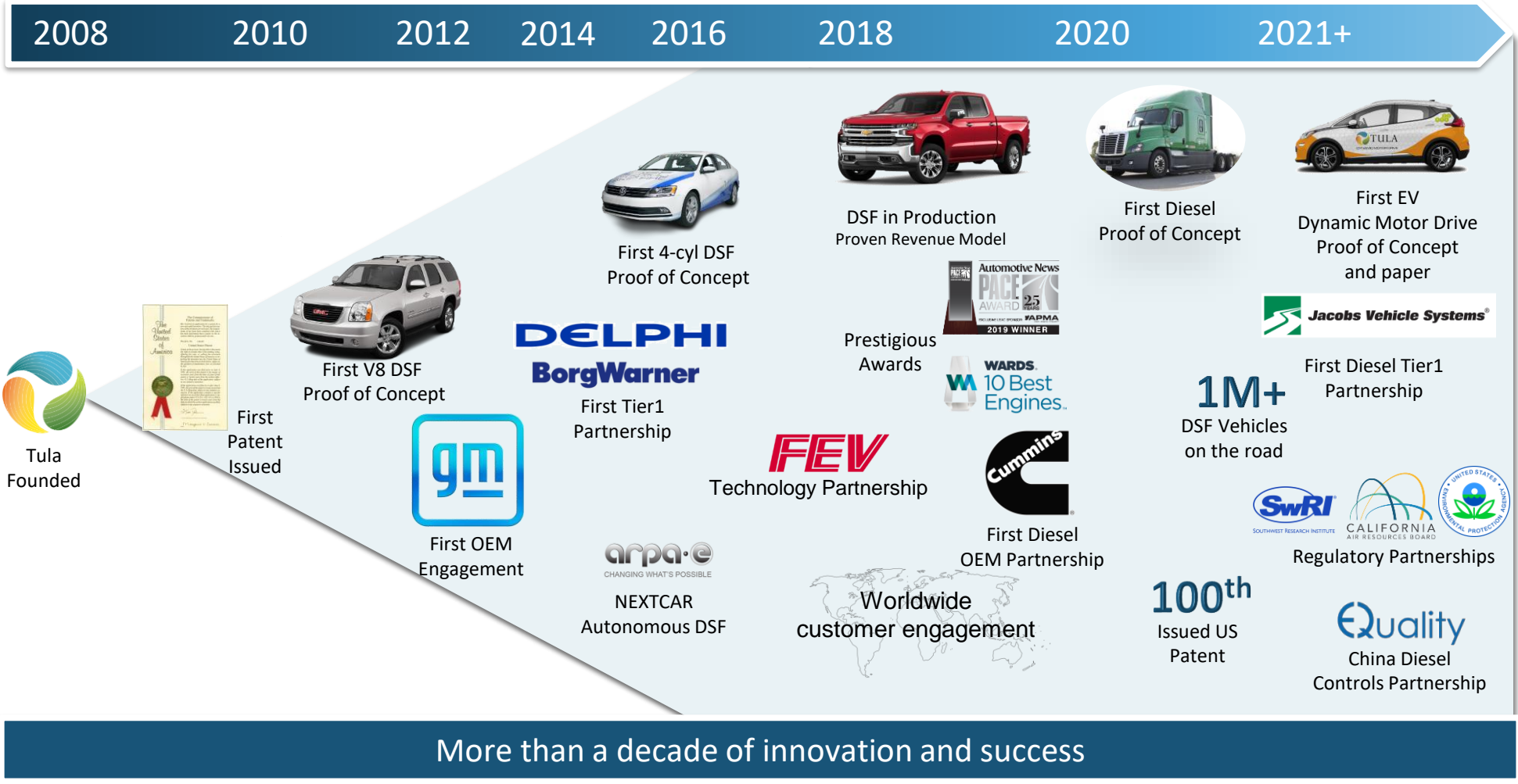


DYNAMIC MOTOR DRIVE

A STRATEGY OPTIMIZING ELECTRIC MOTOR EFFICIENCY

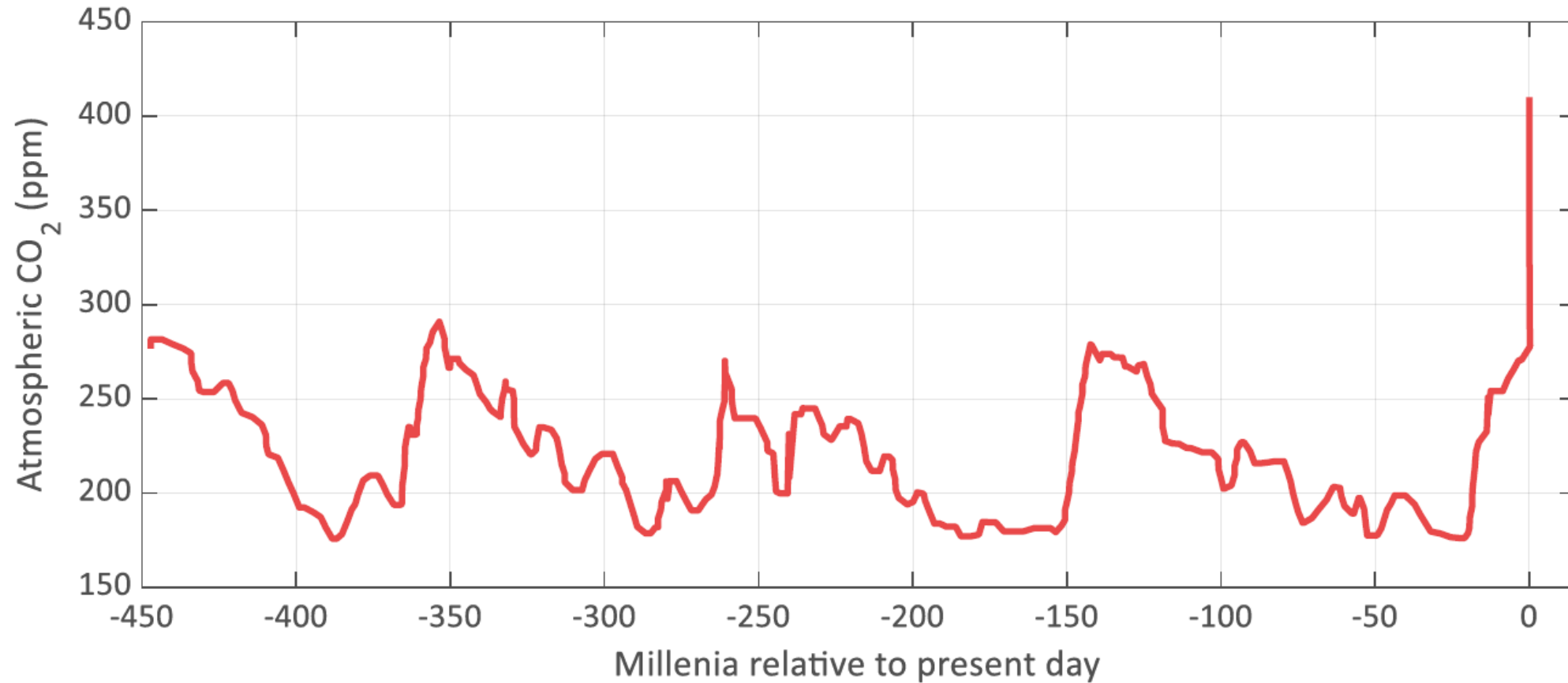
T U L A T E C H N O L O G Y

Tula - Driving Towards the Future



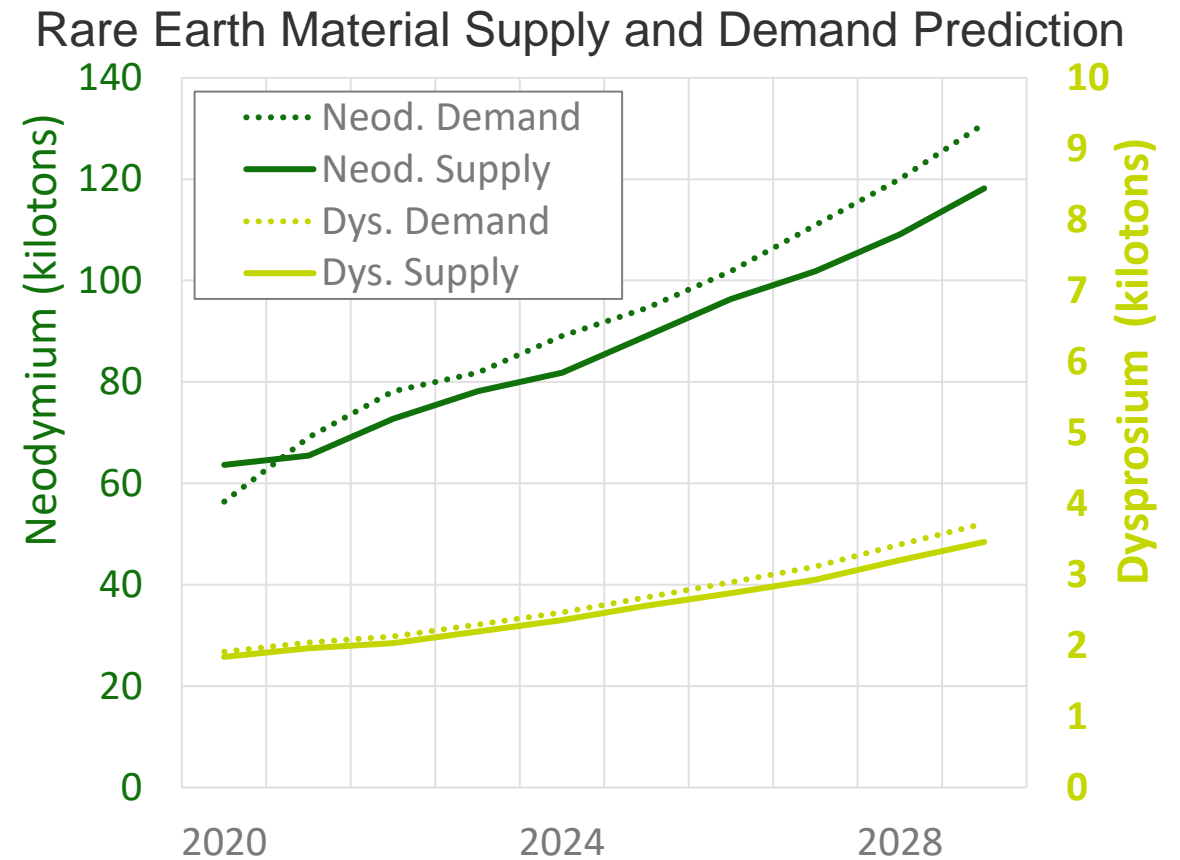
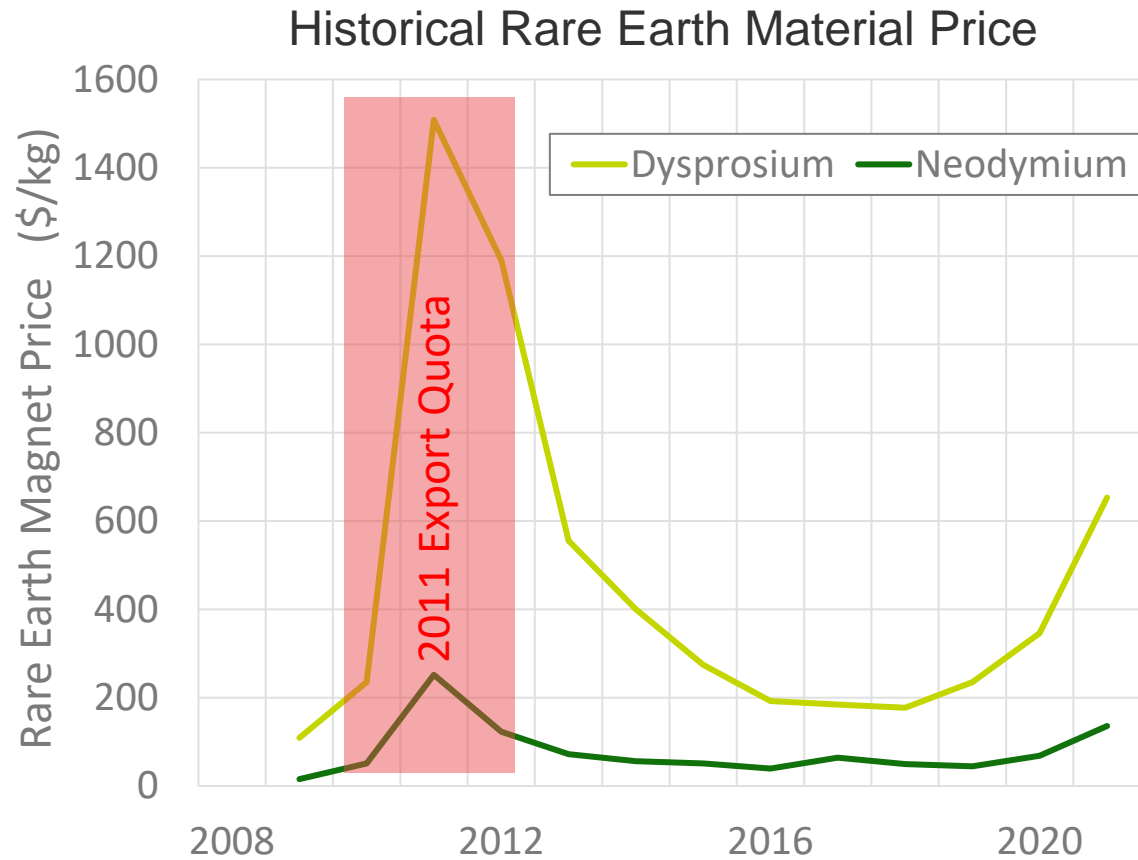
More than a decade of innovation and success

Challenges of Climate Change



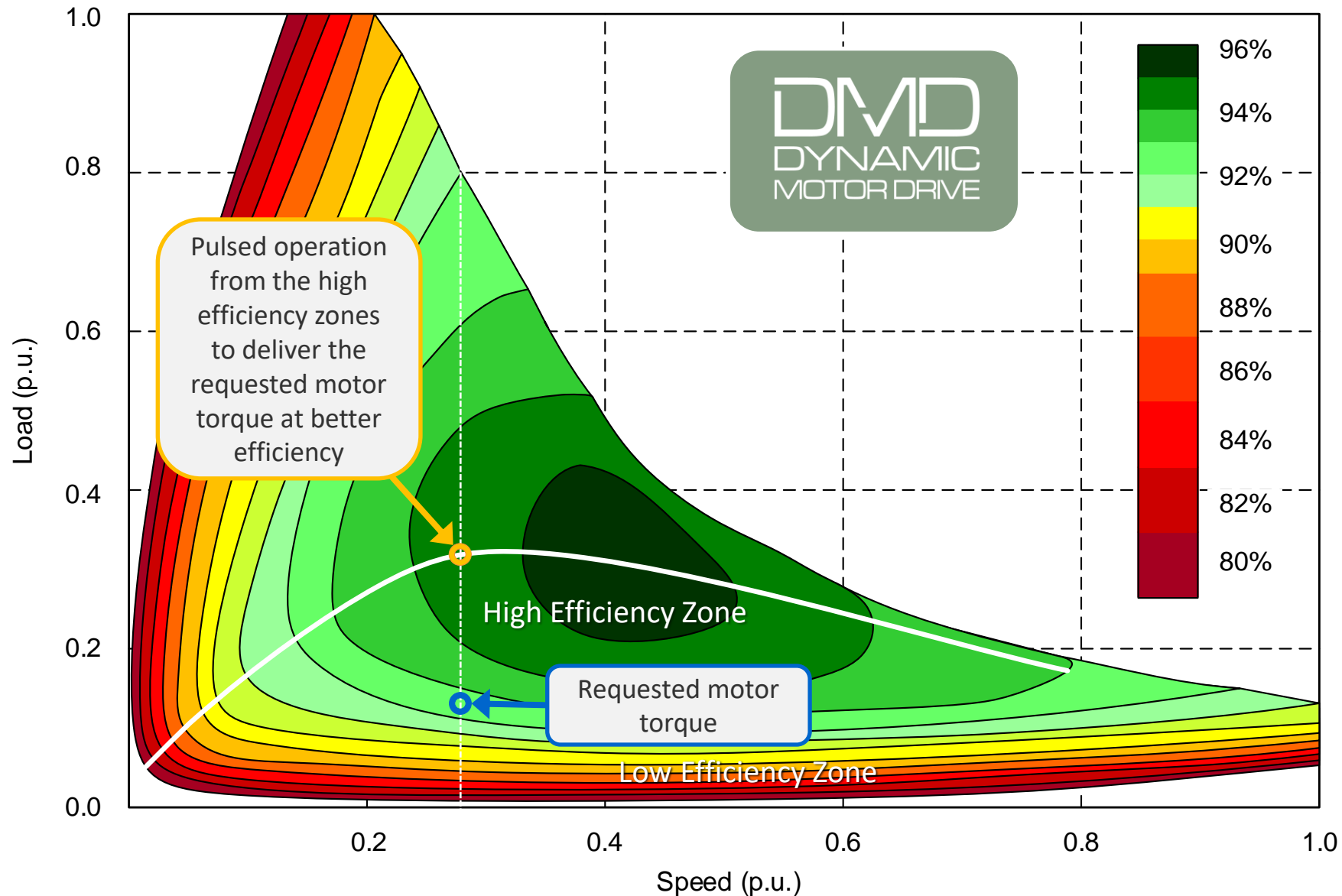
Greenhouse gas emission causes climate change. Automobiles are a major contributor

Conventional Solutions Rely on Rare Materials

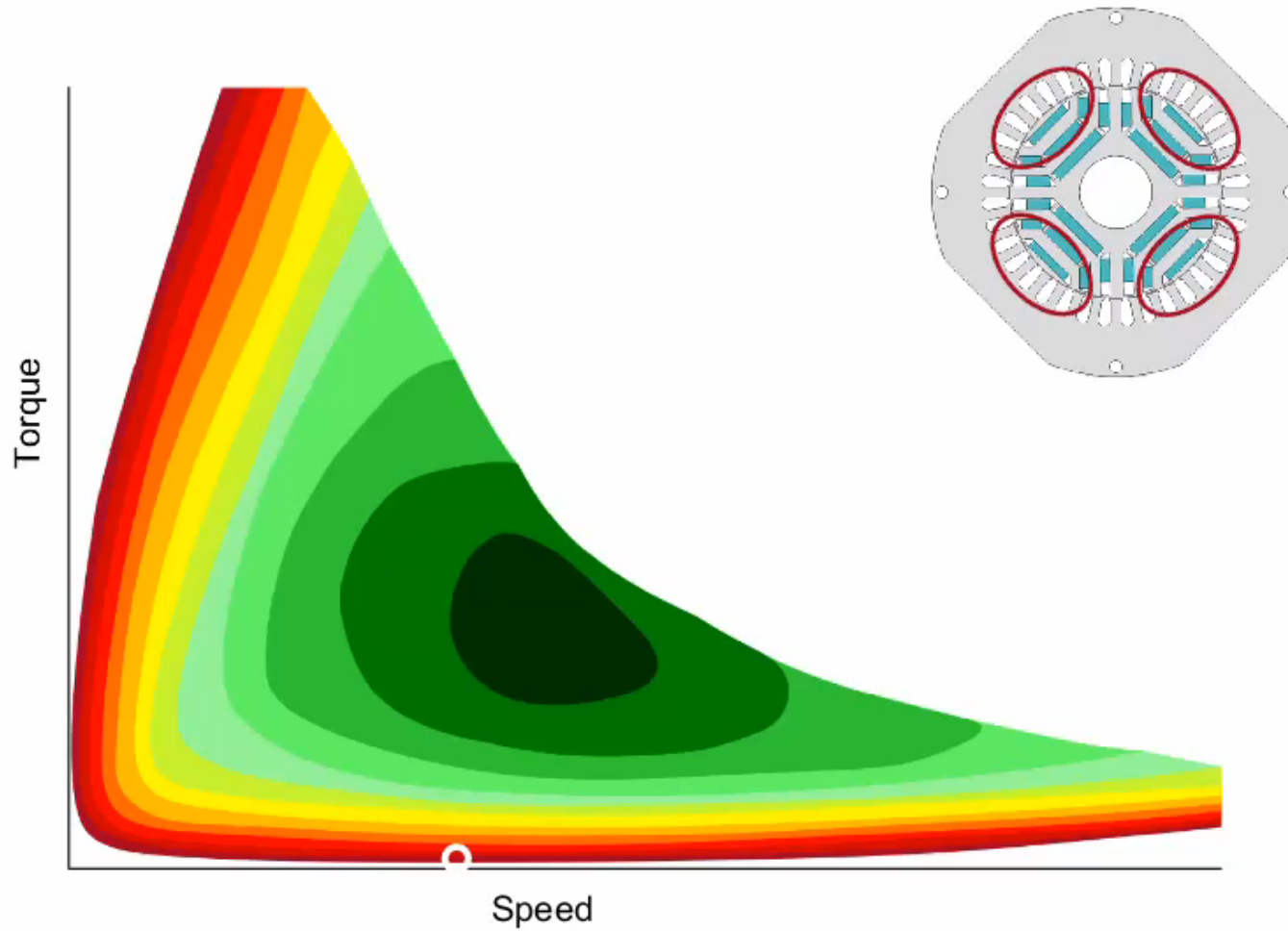


Heavy use of scarce materials can limit the implementation of permanent magnet EVs

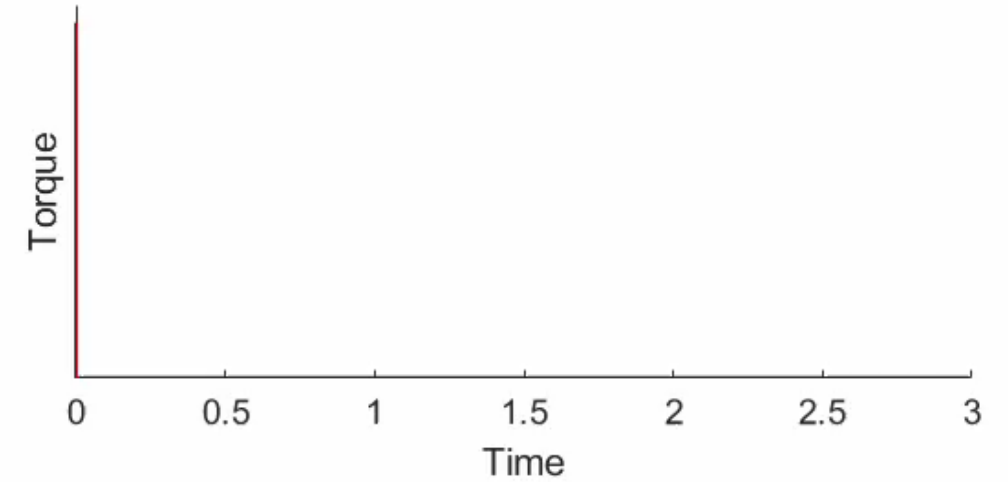
Dynamic Motor Drive (DMD) – The Concept



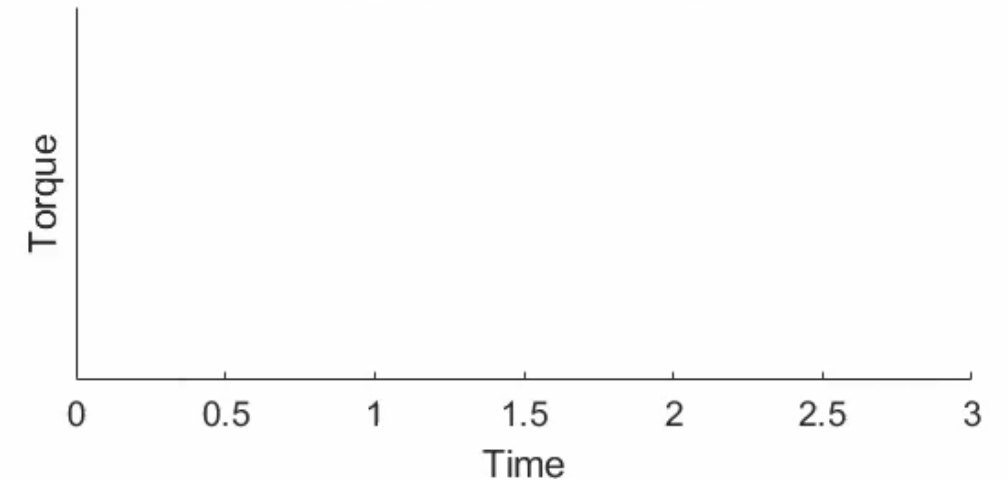
Dynamic Motor Drive (DMD) – The Concept



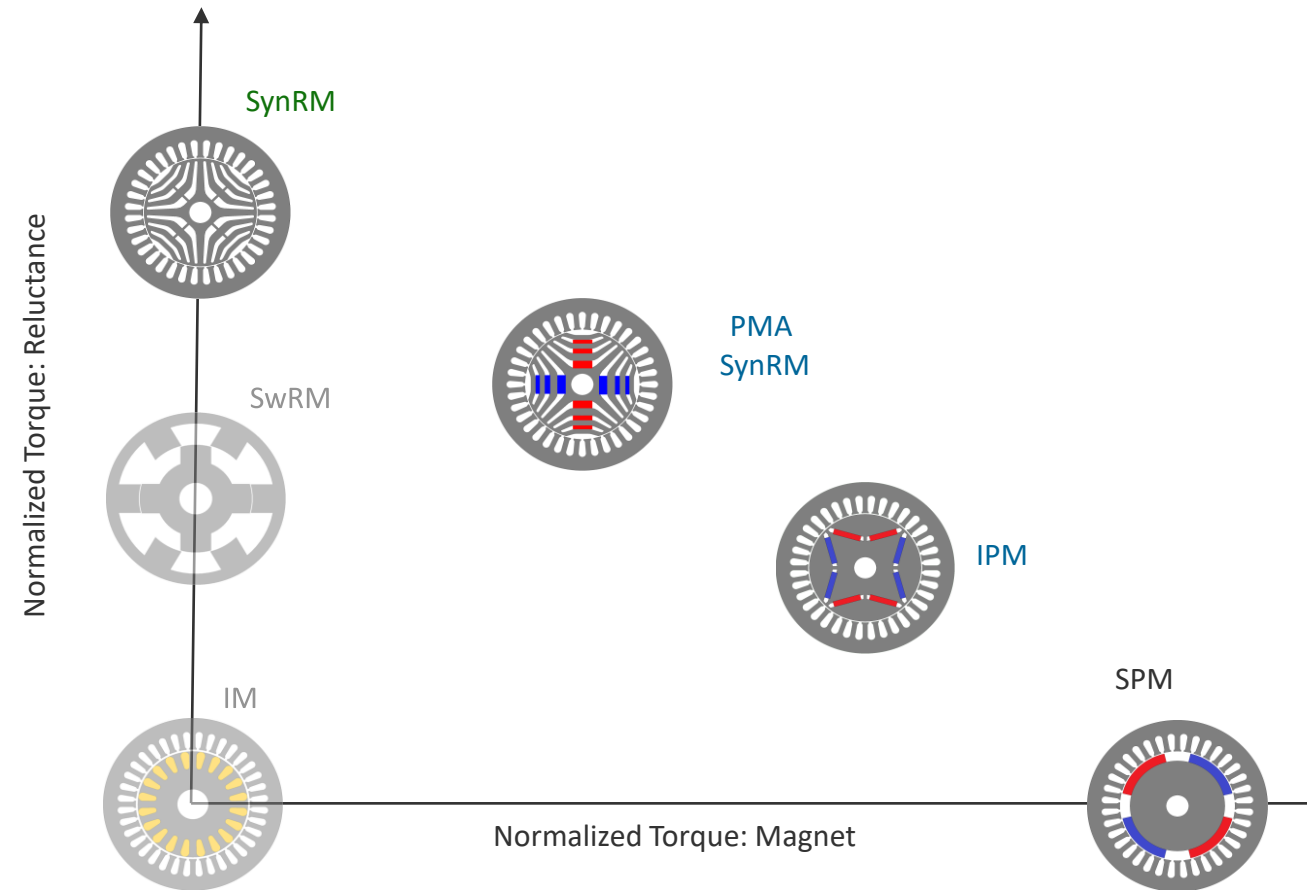
Conventional Operation



Dynamic Motor Drive

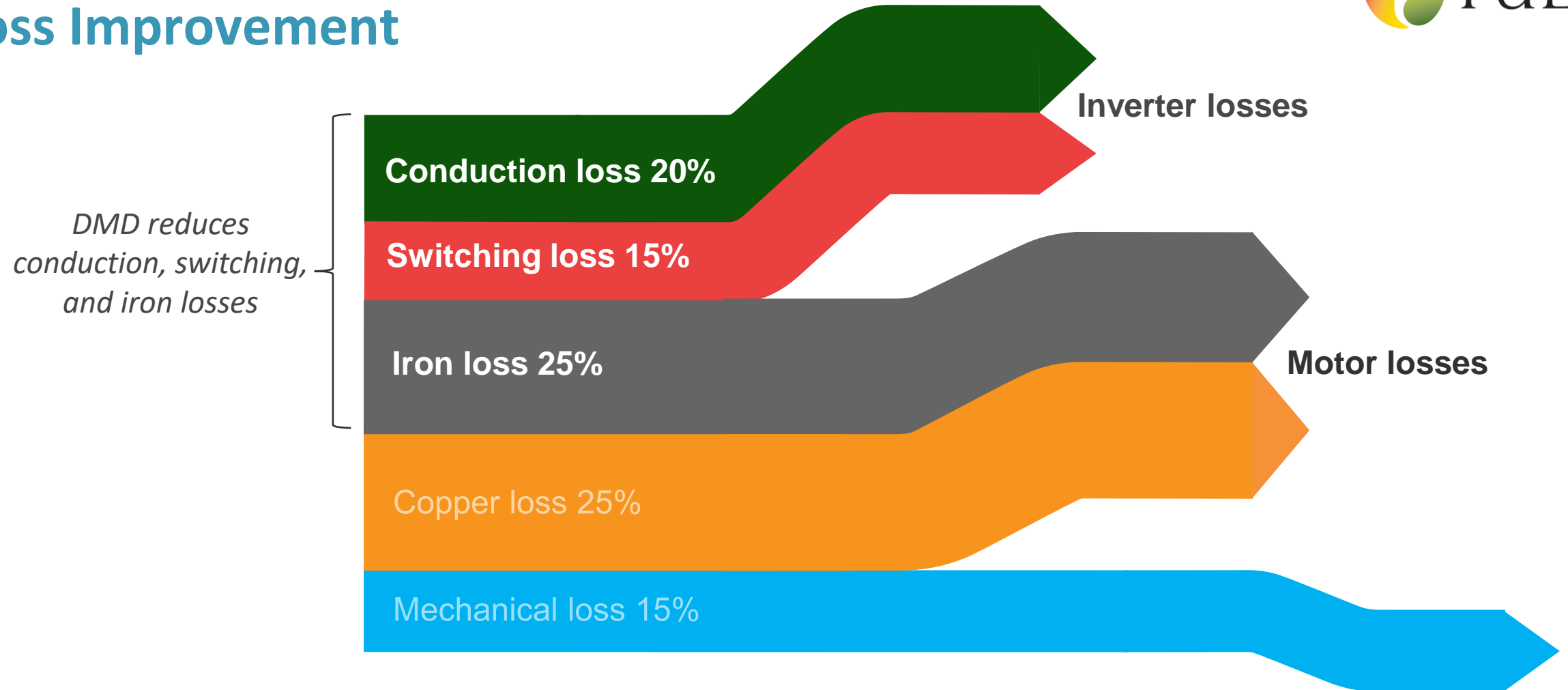


DMD Motor Architecture Selection



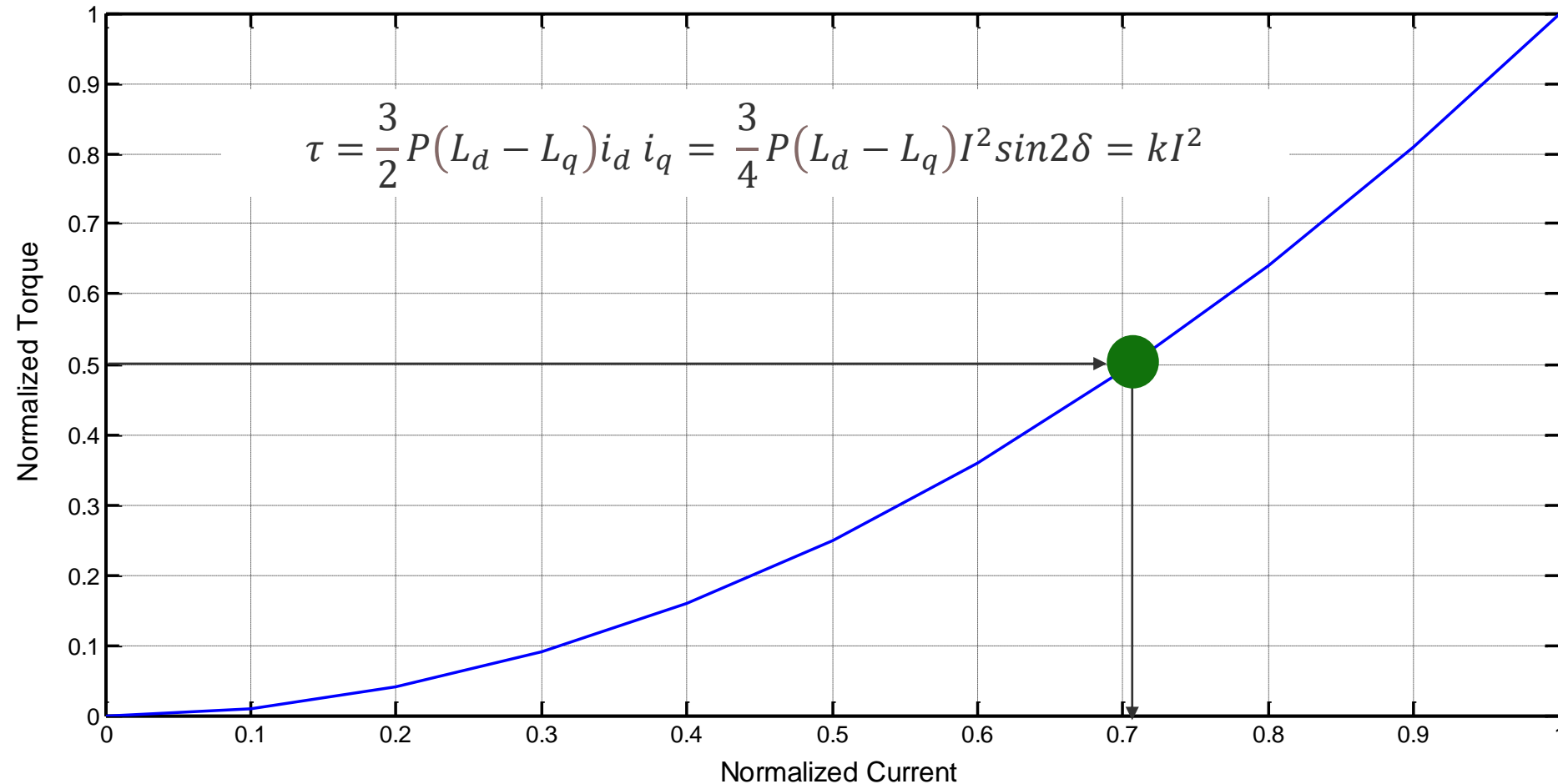
DMD is most effective for Synchronous Reluctance Motors (SynRM)

Loss Improvement



Optimizing these losses improves reluctance motor efficiency significantly

Torque Production of Synchronous Reluctance Motor



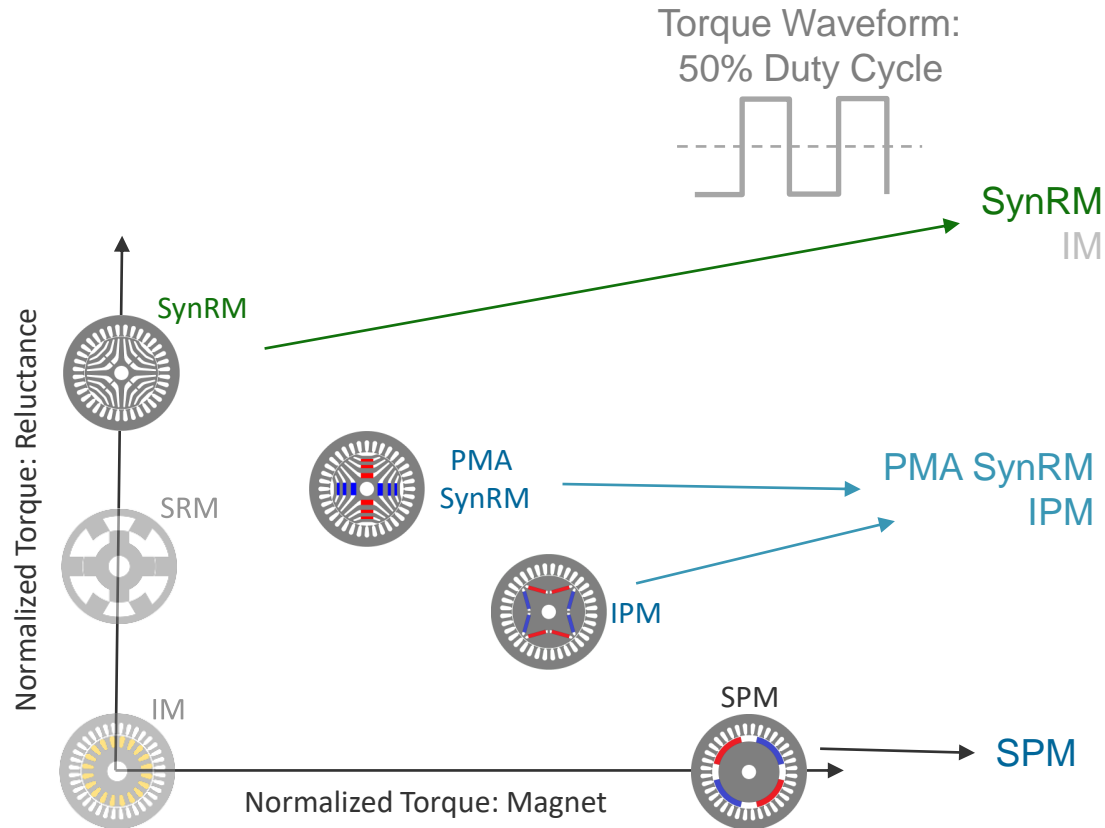
Torque is proportional to current² for SynRM's at moderate loads

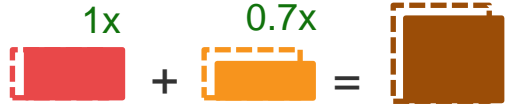
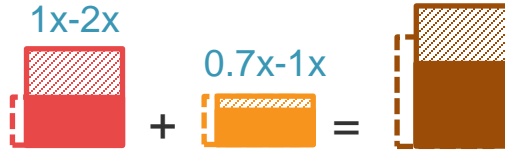

Optimization of Loss Tradeoffs

	Linear to Current	Quadratic to Current
Conduction Loss	$V_{ce0} \left(\frac{1}{2\pi} + \frac{m \cos \theta}{8} \right) I$ DMD	$R_{ce} \left(\frac{1}{8} + \frac{m \cos \theta}{3\pi} \right) I^2$ DMD
Switching Loss	$\frac{f_{sw} V_{dc}}{\pi I_{ref} V_{ref}} (E_{on} + E_{off} + E_{rr}) I$ DMD	-
Copper Loss	-	RI^2 DMD
Hysteresis Loss	$k_h f B^{1.6} V$ DMD	
Eddy Current Loss	-	$k_w \delta^2 f^2 B^2 V$ DMD

Motors using reluctance torque are well suited for DMD

DMD Motor Architecture Selection

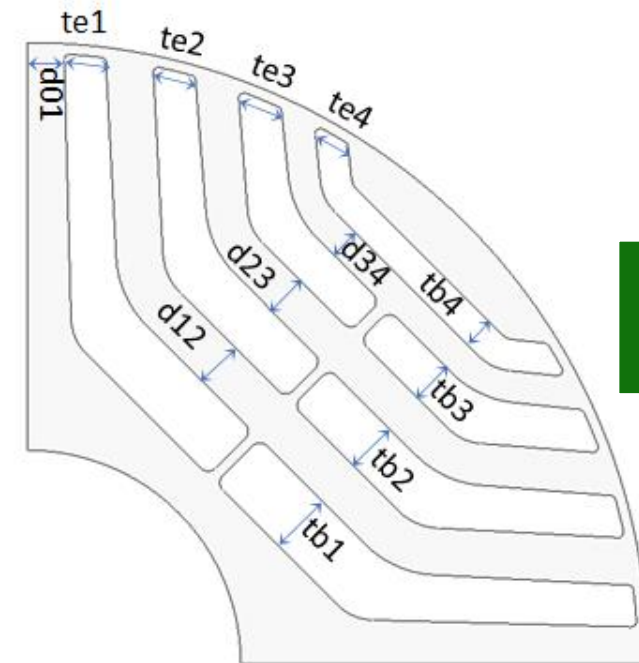
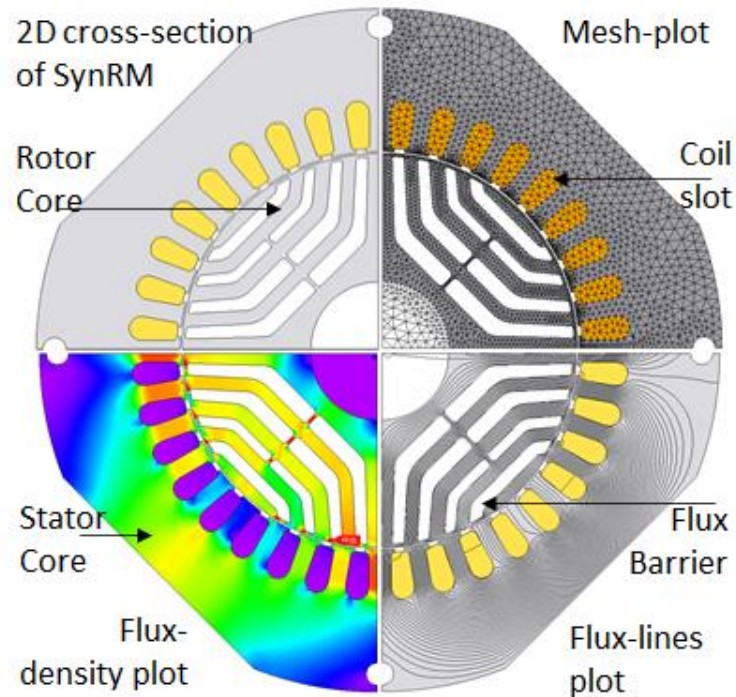


Current for 50% Duty Cycle	Losses			Impact of DMD
	I^2	I	Total	
1.4x	1x	0.7x		Reduced Losses
1.4x - 2x	1x-2x	0.7x-1x		Implementation Specific
2x	2x	1x		Increased Losses

DMD is more effective for motors actively making use of reluctance torque

Tula Designed SynRM

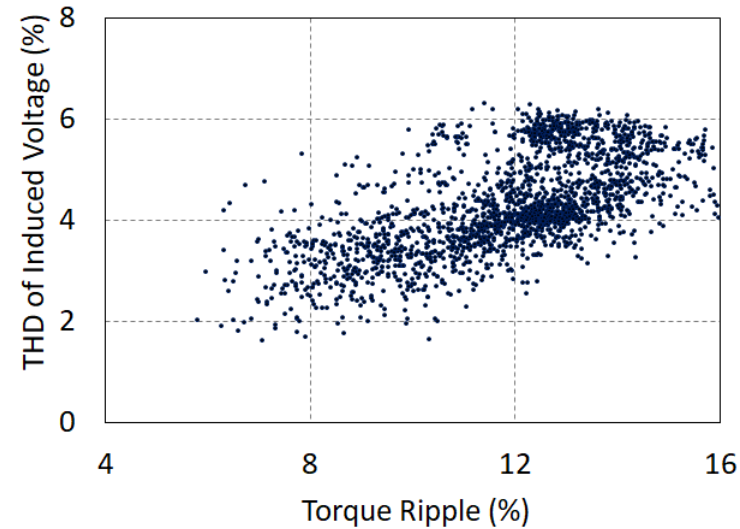
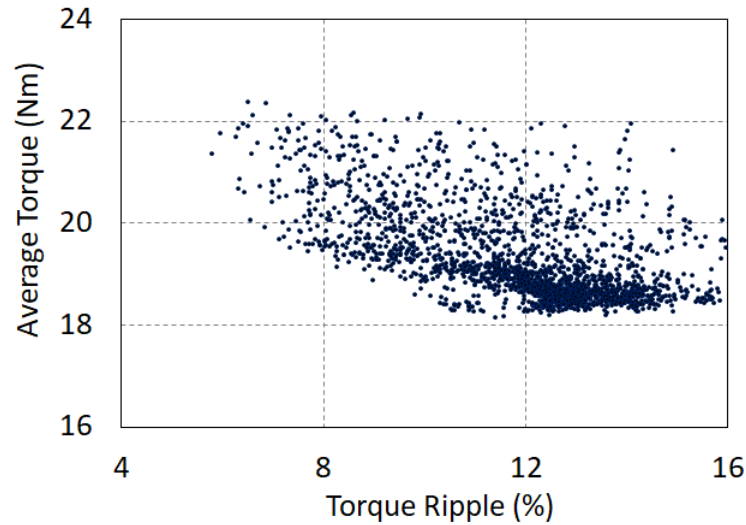
No permanent magnets



Flux barriers increase torque production

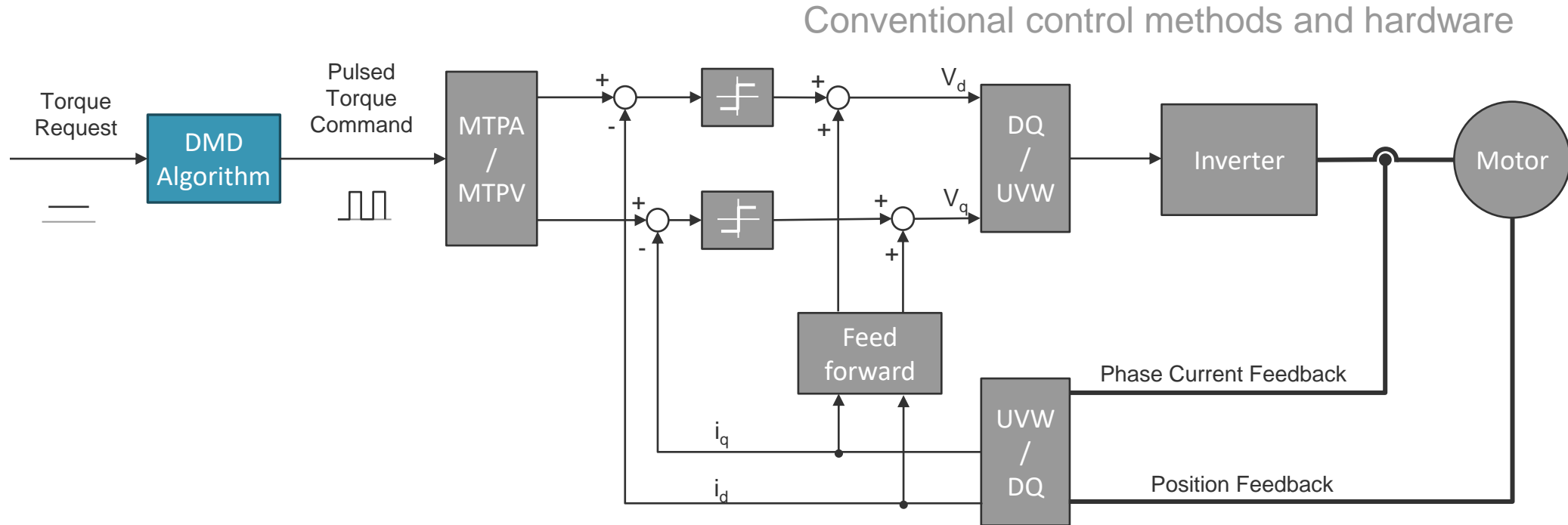
A proof-of-concept motor was designed and built by Tula to prove out DMD Strategy

Synchronous Reluctance Motor (SynRM) Design



As a proof of concept, Tula has designed a 15kW SynRM using a multi-objective genetic algorithm (GA), optimizing torque, torque ripple, and harmonic distortions

Control Optimisation for DMD

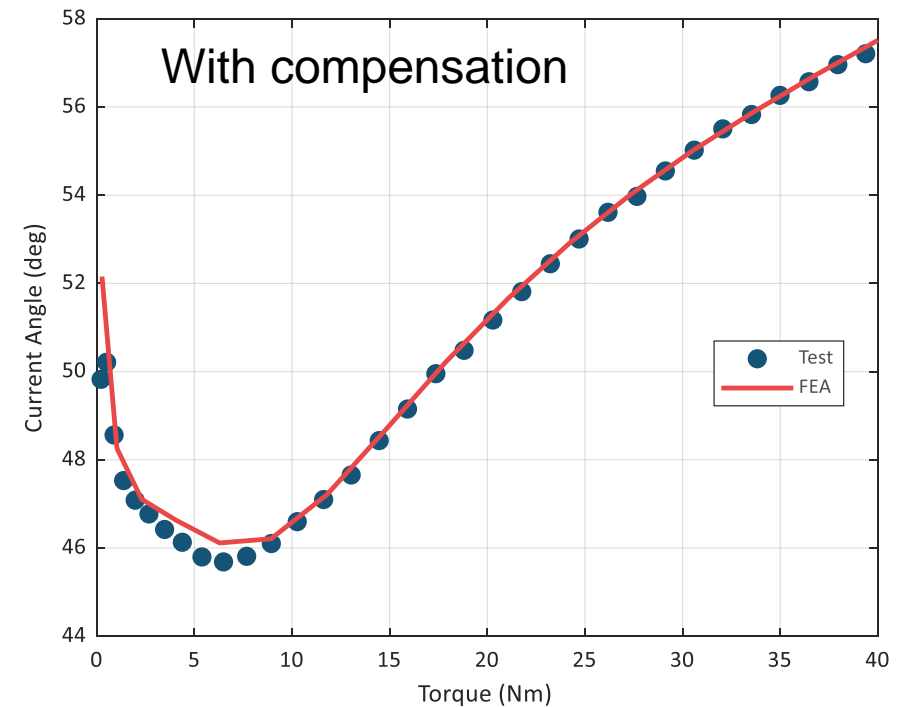
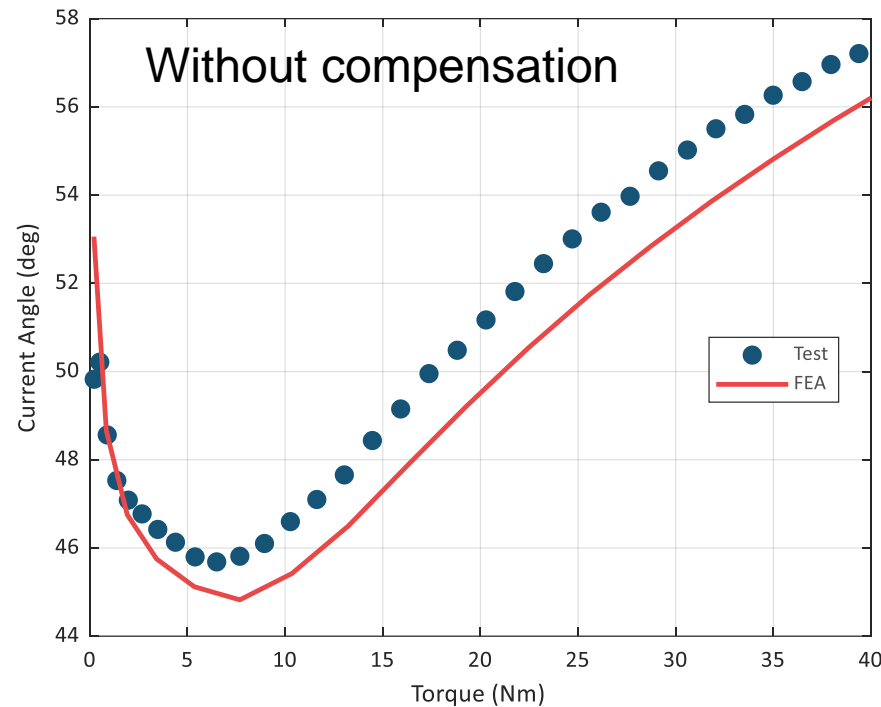


Tula's DMD algorithms were developed to allow implementation with conventional control algorithms

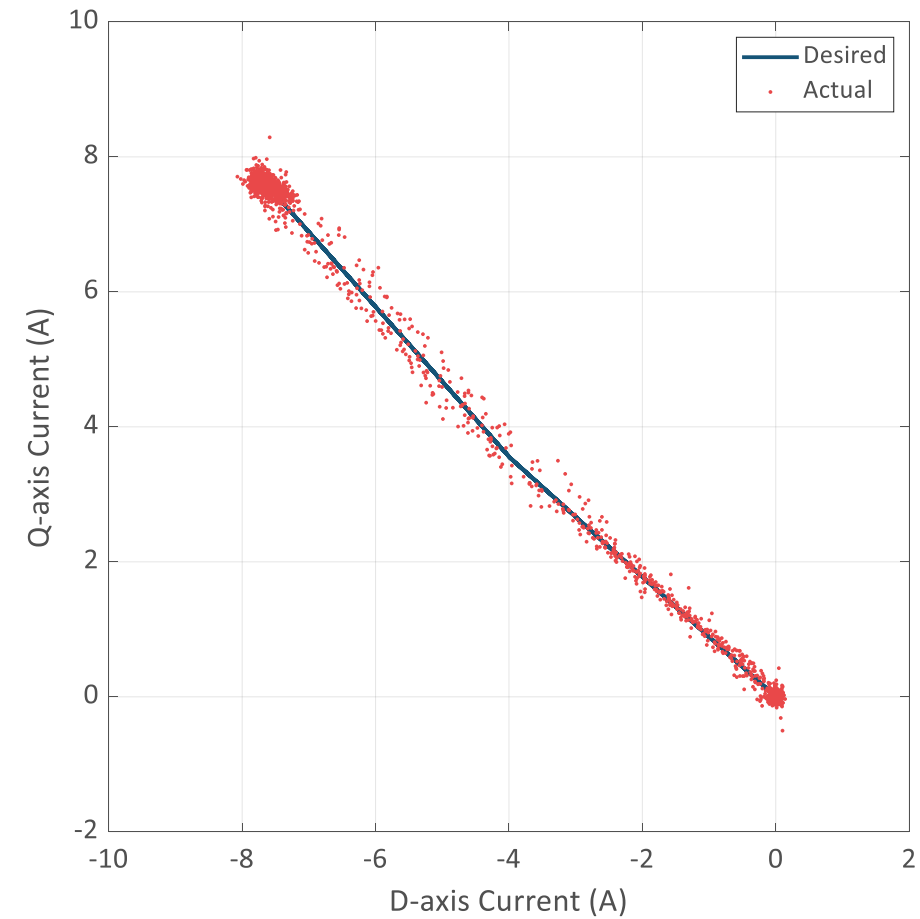
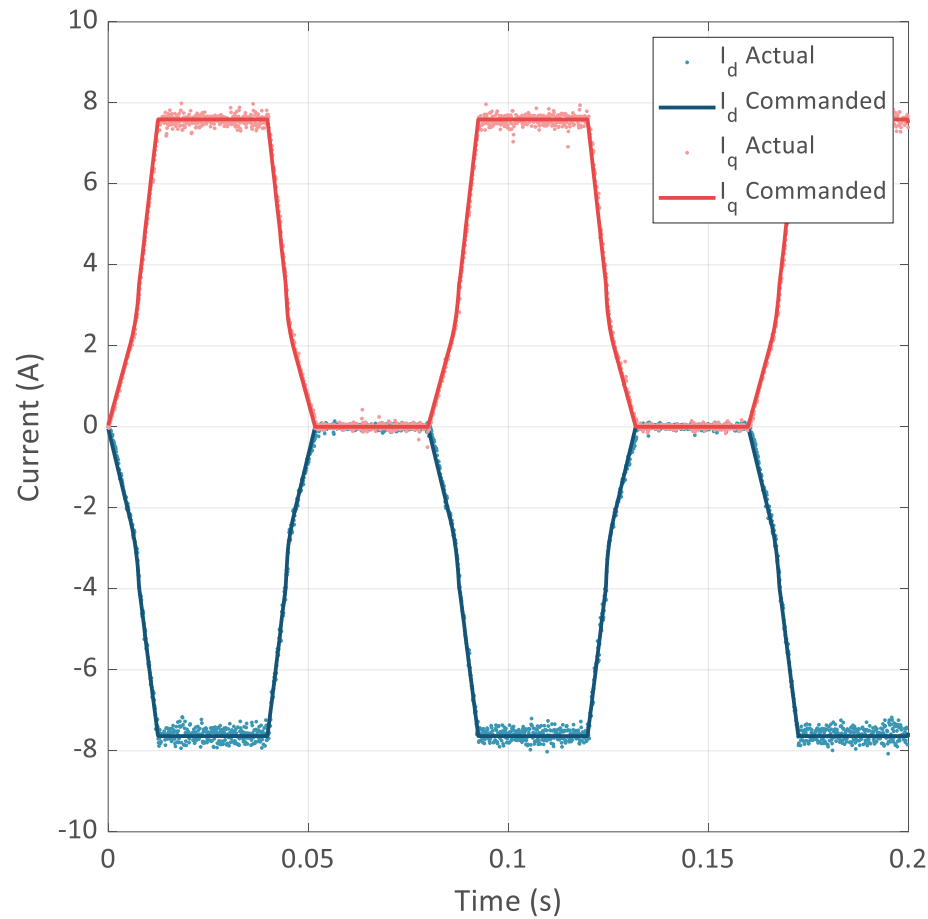
Time-optimized control methods optimize efficiency during transitions between high and low torque

Torque Control Law

- Max torque per Ampere (MTPA) curve generated from Finite Element Analysis has around 1° error from test results
- This inaccuracy is corrected by compensating the iron loss model

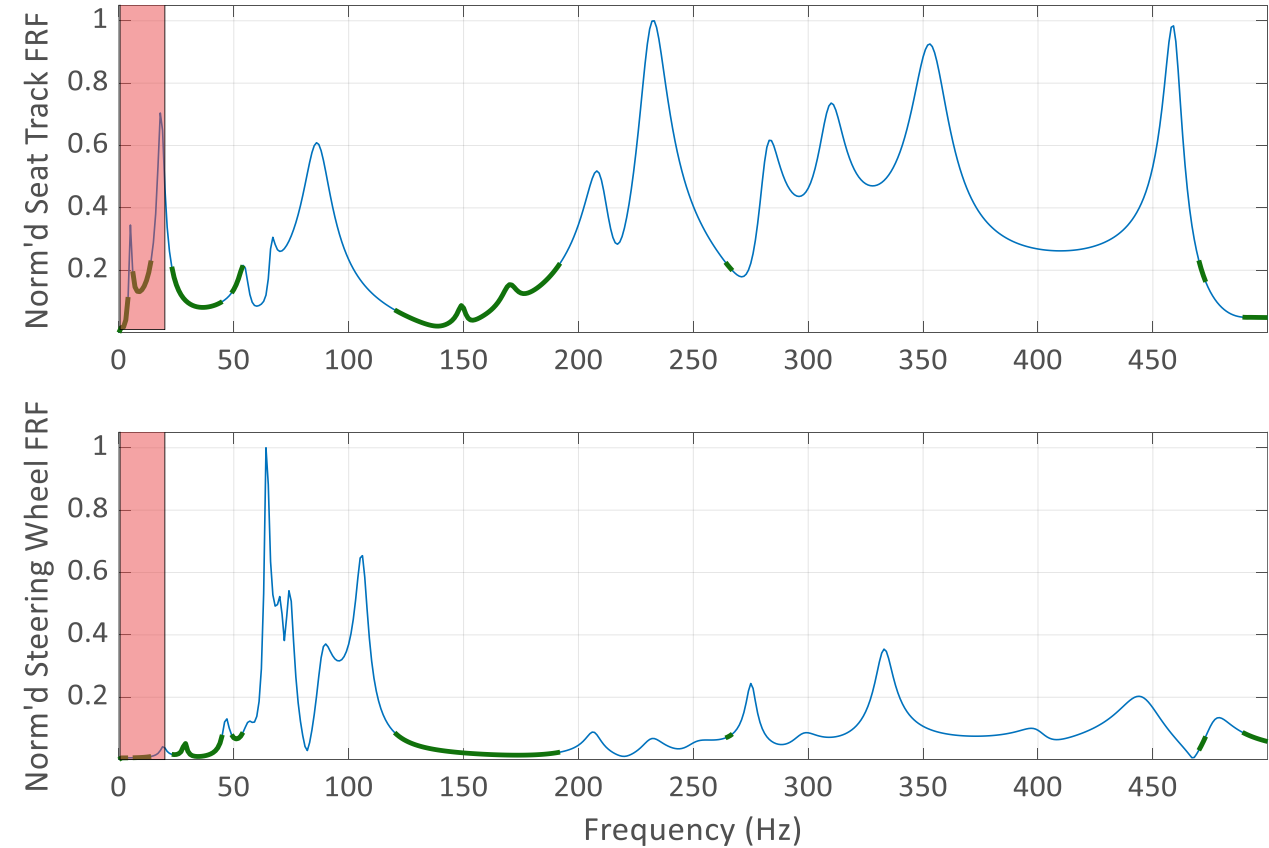
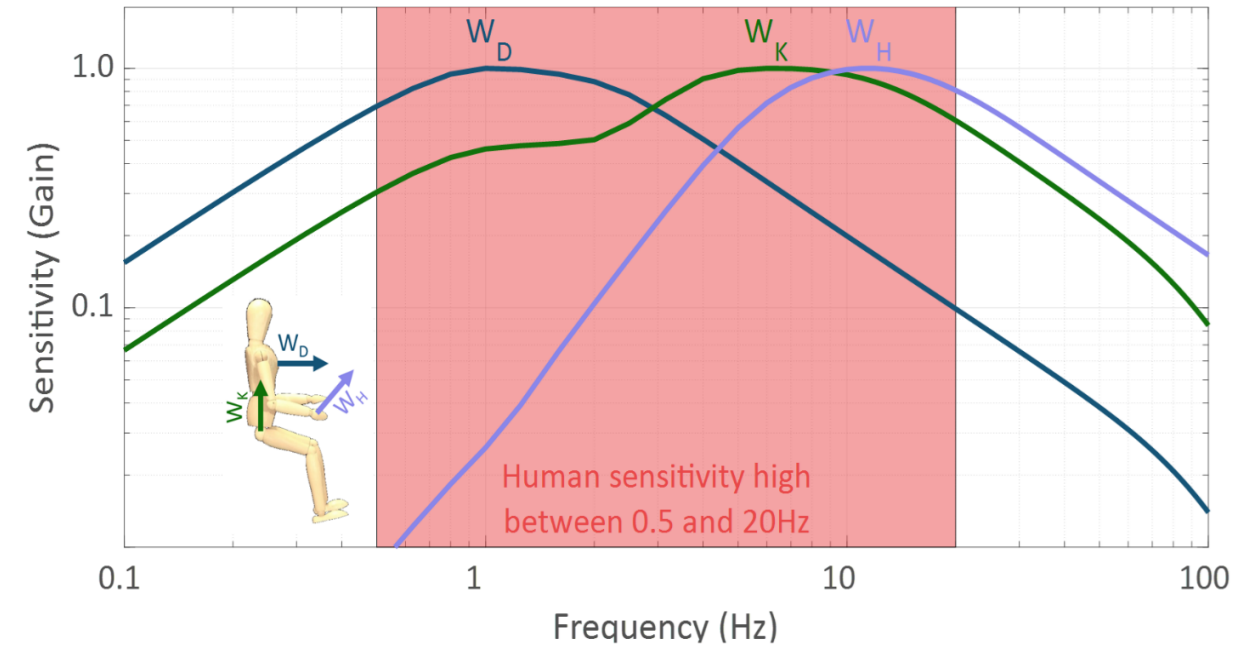


Current Control Achieving Desired Response Speed



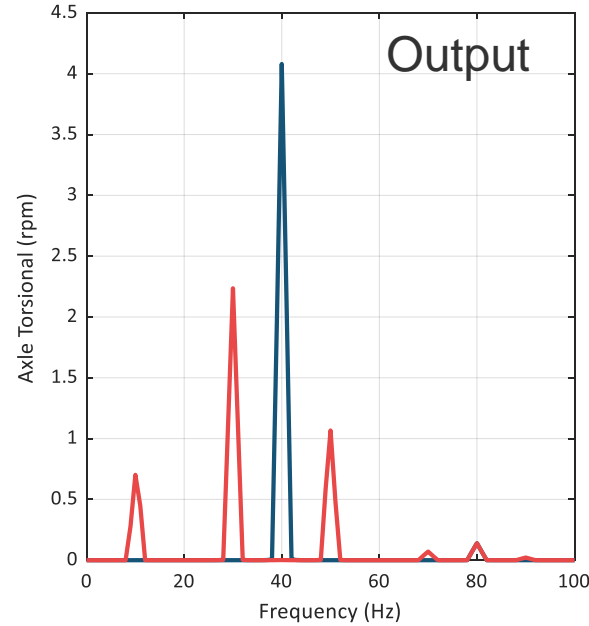
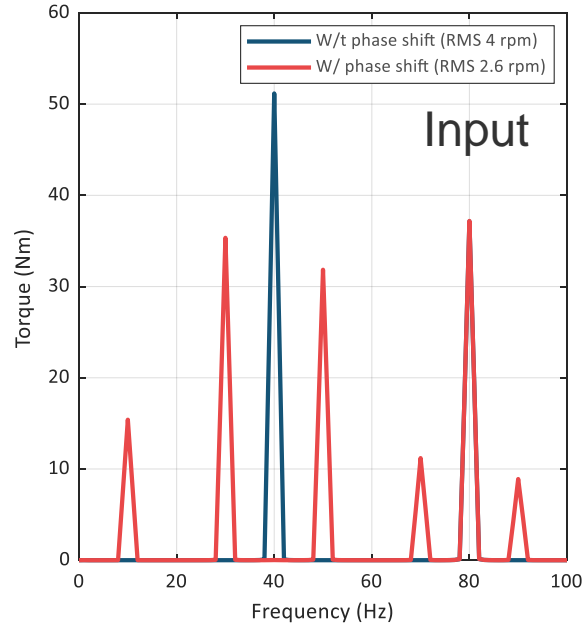
Excellent current tracking realized by deadbeat control

Vehicle Sensitivity and Human Perception

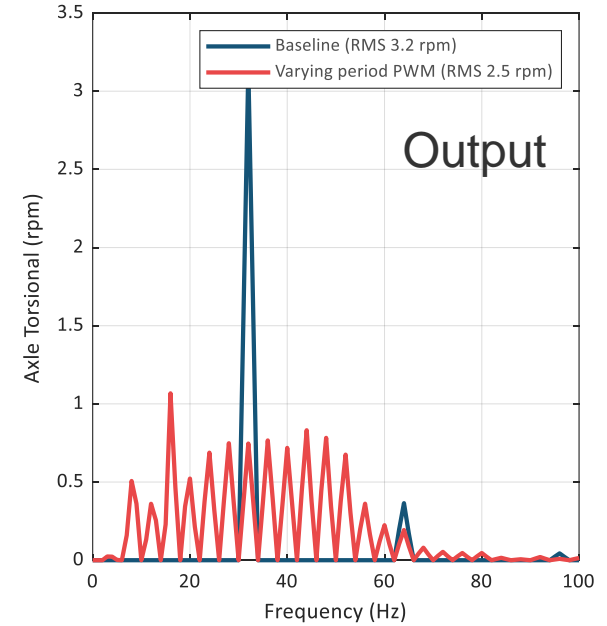
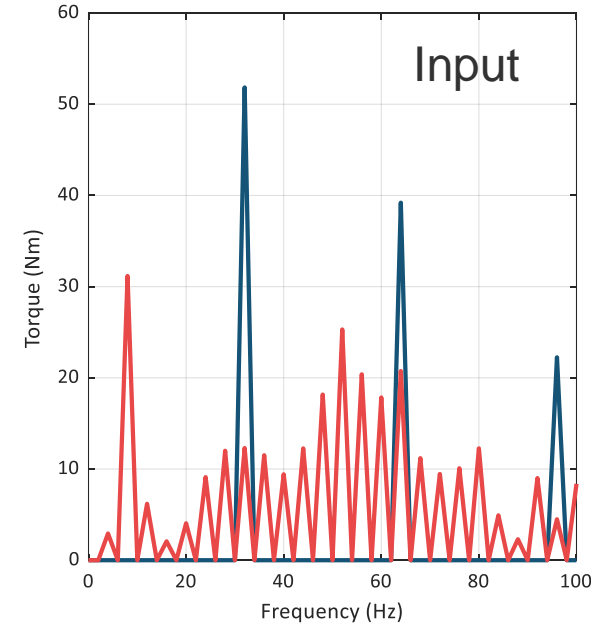


Torque modulation frequency selected has less human sensitivity

Vibration Mitigation Strategies



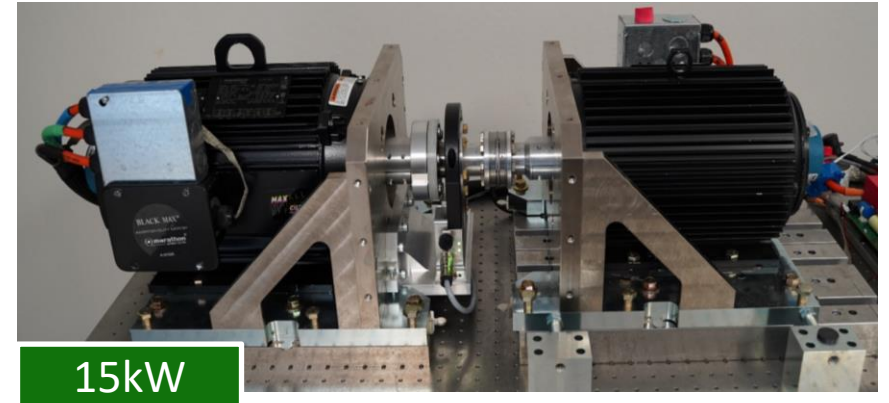
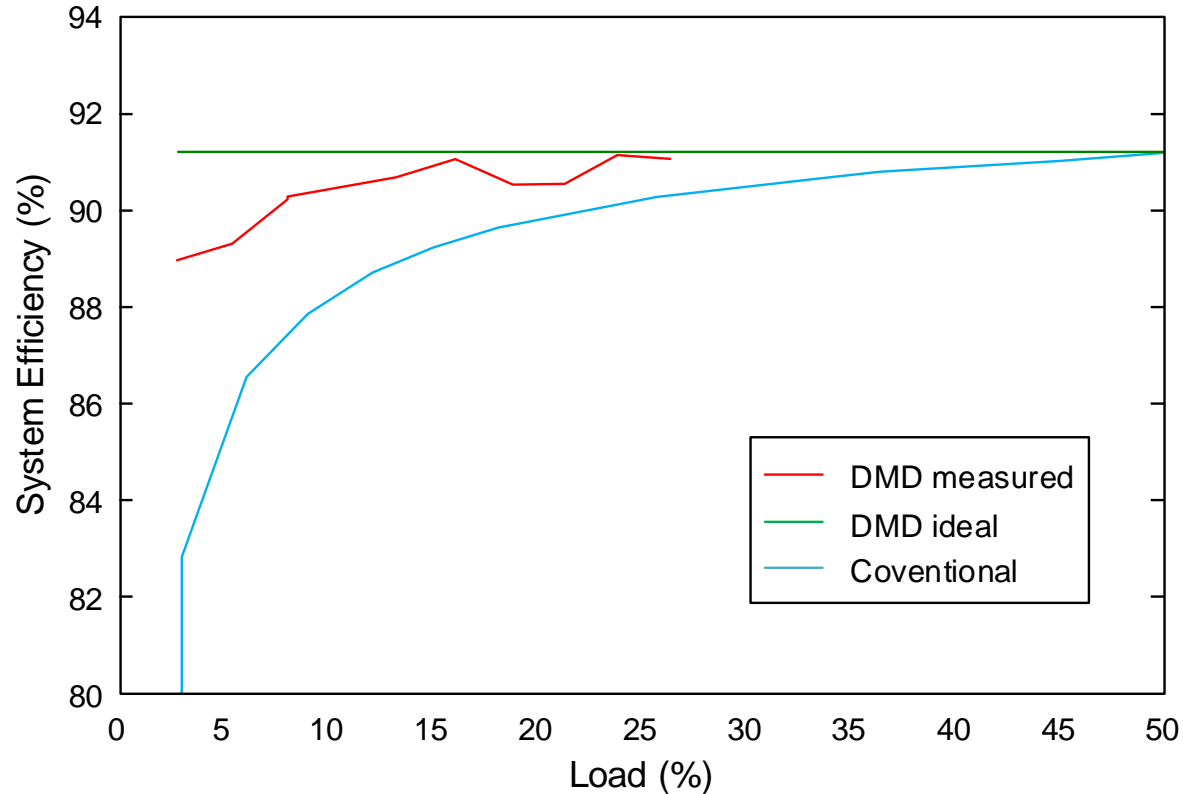
Switching modulation waveform phase between 0 and 180 degrees every 3 cycles



Changing torque modulation frequency randomly between 4 Hz and 40 Hz

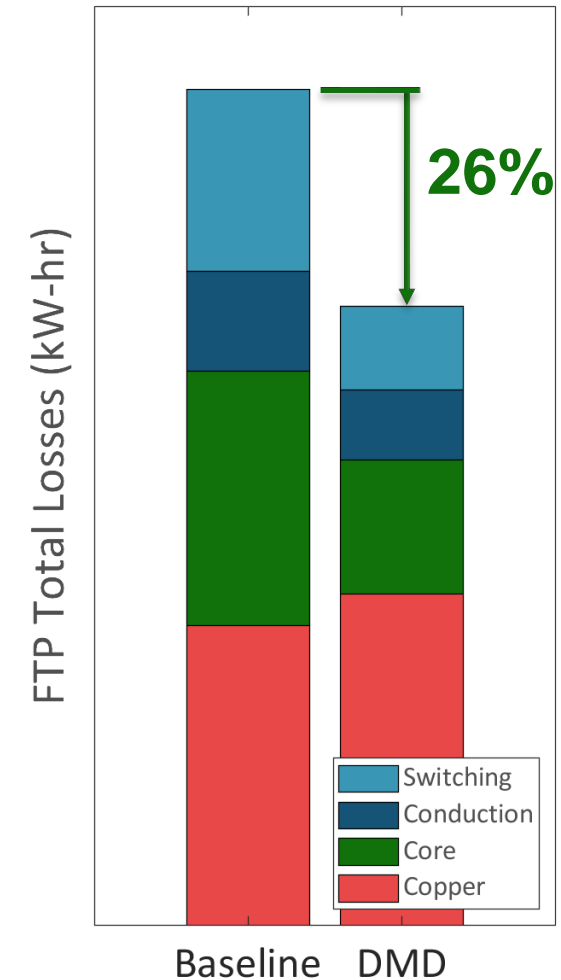
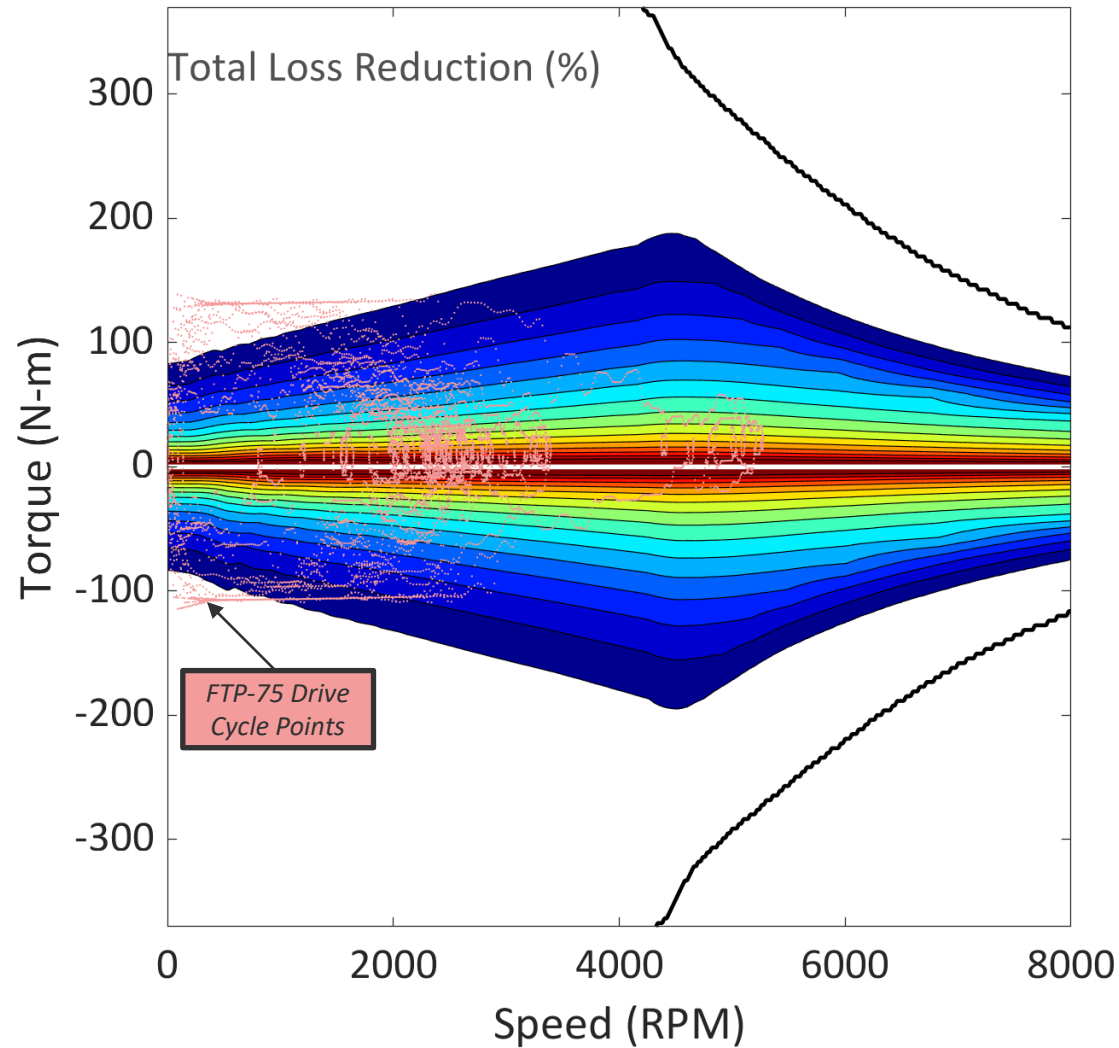
Phase shifting and frequency changing are effective to lower and spread the vibration frequency

Test Results of Efficiency Improvement of 15kW SynRM



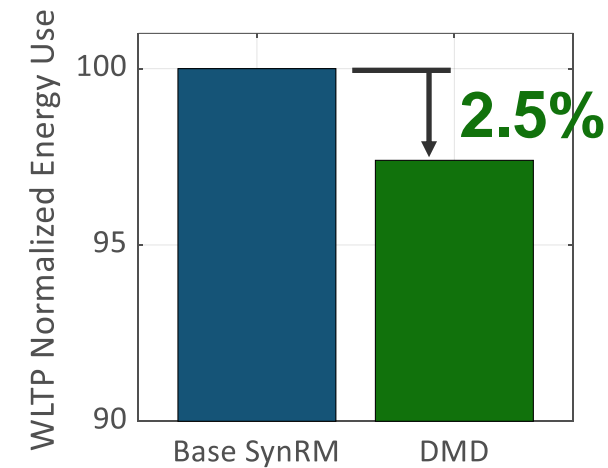
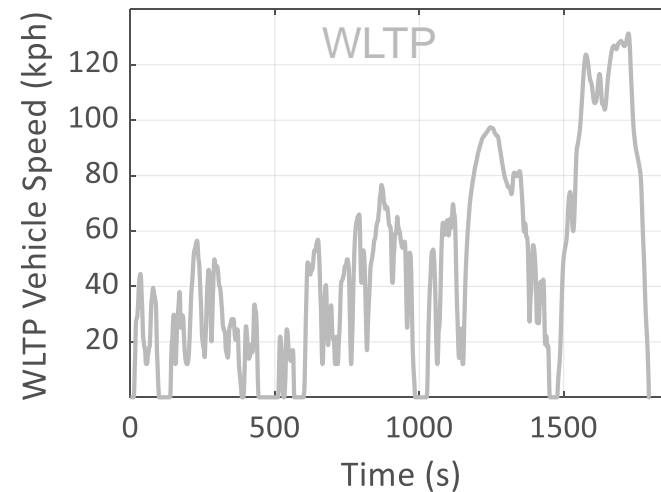
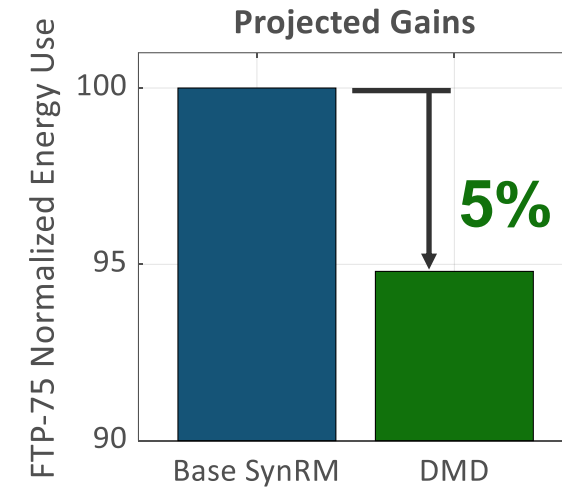
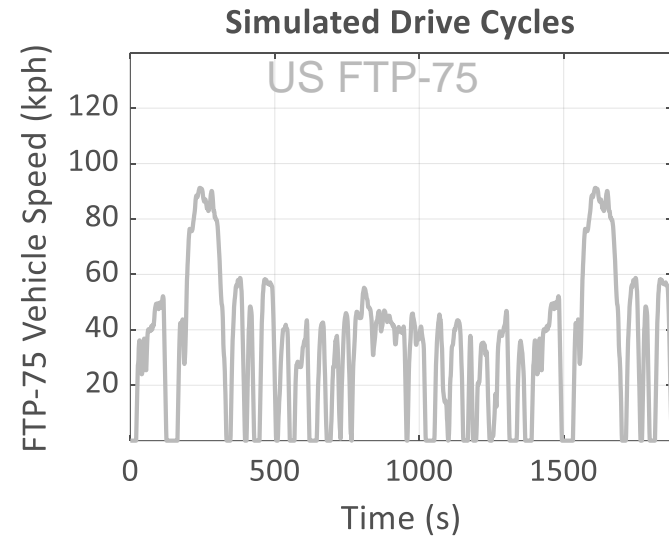
- Up to 7% efficiency improvement is verified at low loads with initial controller
- Advanced controller is under developing to narrow the gap to ideal values

Simulation Results on Efficiency Improvement



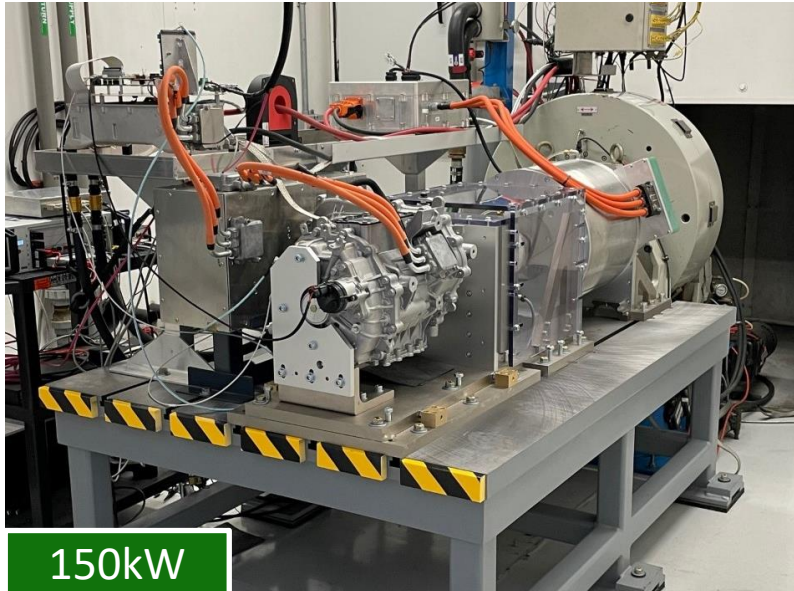
Drive cycle losses are reduced by 26%

Simulation Results on Efficiency Improvement



Substantial energy usage reduction of 2.5-5% for a 150kW application

Future Plan on Full-Sized Traction Motor Test



Our 150kW vehicle traction-motor development dyno is now operable and collecting initial data



We have implemented control on two demonstration Bolts

DMD Enables Better Efficiency

- Dynamic Motor Drive is a control strategy optimizing motor and inverter system efficiency
- It requires no additional hardware and is easy to implement in software with IP licensed from Tula
- Significant efficiency improvements on relevant drive cycles are achieved, helping to reduce or eliminate rare earth material dependence and downsize the battery capacity required
- The strategy makes use of a very fast response speed of the proposed current controller to realize optimal efficiency at both steady and transient states
- Vibration issues can be mitigated by using industry-proven techniques developed with Tula's Dynamic Skip Fire technology